

I. AMENDMENT

In the Specification:

Please amend the specification as follows:

[13] To illustrate the third scenario, assume that after coarse positioning, the head **14** is over the track **22_{n+1}** at a position Q, which is a radial distance $-D_q$ from the center M of the track **22_{n+2}** — [[“-”]] “-” indicates that D_q and D_r are in opposite directions from M. Therefore, because $\text{Mag } B > \text{Mag } A$, the disk drive **10** “knows” that the head **14** is closer to the track **22_{n+1}** than to the track **22_{n+3}**, and thus generates a corresponding position-error signal. In response to this position-error signal, the head-position circuit that causes the motor **18** to move the head **14** from Q toward/to the center M of the track **22_{n+2}**.